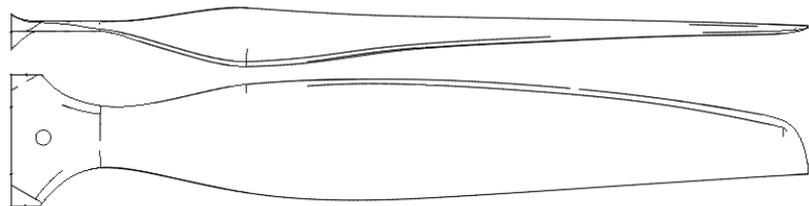


PROPELLER

16x5.5 3B MC

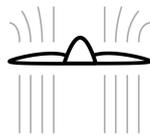
PN: 3160552, 3160553



*Illustrative image only



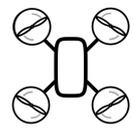
29 g
Mass



11.4 kgf
Max Thrust



16.0"
Diameter



Multicopter

Engine/Motor type: Electric

Rotation direction: Counter-clockwise and Clockwise available (Direction Guide)

Mass [g]: $29 \pm 10.0\%$

Moment of inertia [kgm^2]¹: $5.99\text{e-}04$

Core diameter [mm]: - (Drilling guide)

Limit hover RPM²: 11200

Limit forward speed [m/s]: Not calculated

Working temperature [°C]: from -20°C to 60°C

Production method: Wet layup

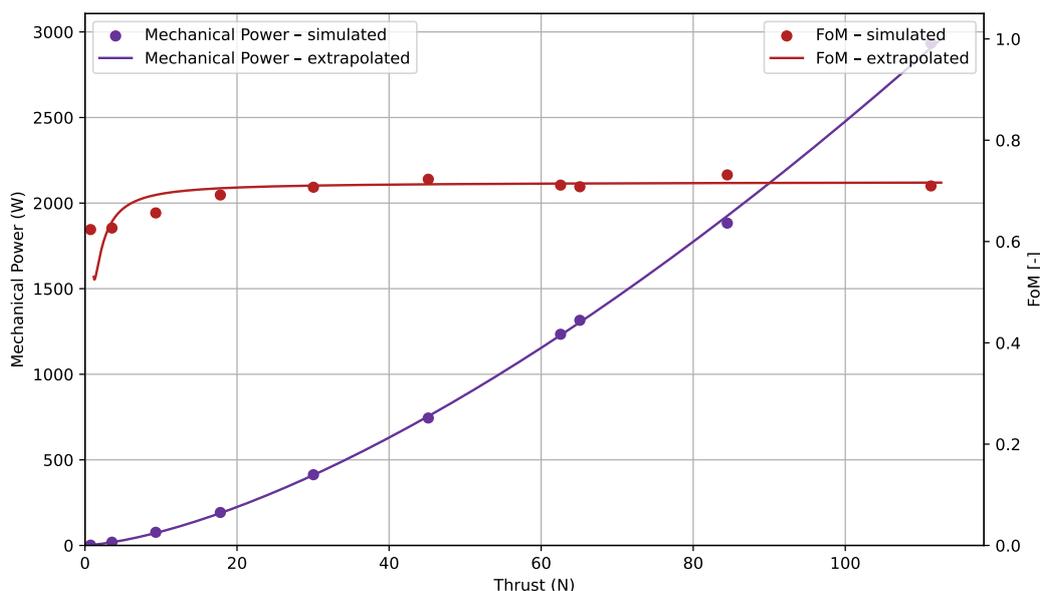
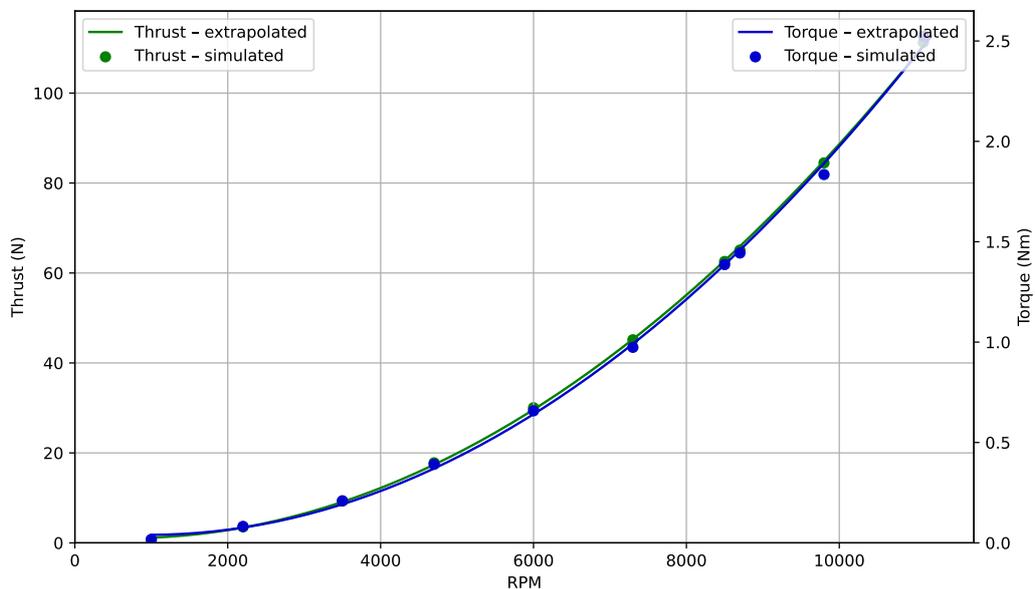
¹ Moment of inertia is only an estimation: $I = \frac{1}{24} \cdot \text{mass} \cdot \text{diameter}^2 \cdot n^{\circ} \text{ of blades}$

² RPM is limited by tip speed; forward speed reduces the limit.

For more information or custom propeller options, contact info@mejlizk.eu.
Operation manual: Propeller Maintenance and Repair Manual

Static Performance Data

Simulated data



$$\text{Thrust (RPM): } 1.006e - 06 \cdot RPM^2 + -1.350e - 03 \cdot RPM + 1.506e + 00$$

$$\text{Torque (RPM): } 2.370e - 08 \cdot RPM^2 + -4.573e - 05 \cdot RPM + 6.198e - 02$$

$$\text{Mechanical power (RPM): } \frac{2\pi \cdot \text{Torque}[\text{Nm}] \cdot RPM}{60}$$

Formulas used to calculate FOM : $C_T = \frac{T}{\rho RPS^2 D^4}$ $C_P = \frac{P_{mech}}{\rho RPS^3 D^5}$ $FOM = \sqrt{\frac{2}{\pi} \frac{C_T^{3/2}}{C_P}}$